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# Oscillation of Second-Order Neutral Differential Equations

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## Abstract

We study oscillatory behavior of a class of second-order neutral differential equations relating oscillation of these equations to existence of positive solutions to associated first-order neutral differential

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inequalities. Our assumptions allow applications to differential equations with both delayed and advanced arguments, and not only. New theorems complement and improve a number of results reported in the literature. Two illustrative examples are provided.

**Key words:** Oscillation, neutral differential equations, delayed arguments; advanced arguments; positive solutions; comparison.

**AMS Subject Classification:** 34K11

## 1 Introduction

In this paper, we study the oscillation of a class of functional differential equations

$$(r(t)[x(t) + p(t)x(\tau(t))])' + q(t)x(\sigma(t)) = 0 \quad (1)$$

in the case

$$\lim_{t \rightarrow \infty} R(t) < \infty, \quad (2)$$

where  $R(t) = \int_{t_0}^t (r(s))^{-1} ds$ . The increasing interest in oscillatory properties of solutions to second-order neutral differential equations is motivated by their applications in the engineering and natural sciences. We refer the reader to the papers [1]-[15] and the references cited therein.

We assume that the following assumptions are satisfied:

$$(H_1) \quad r, p, q \in C([t_0, \infty)), r(t) > 0, 0 \leq p(t) \leq p_0 < \infty, q(t) > 0;$$

$$(H_2) \quad \sigma \in C^1([t_0, \infty)), \lim_{t \rightarrow \infty} \sigma(t) = \infty;$$

$$(H_3) \quad \tau \in C^1([t_0, \infty)), \tau'(t) \geq \tau_0 > 0, \tau \circ \sigma = \sigma \circ \tau.$$

Throughout the paper, we use the notation  $z(t) := x(t) + p(t)x(\tau(t))$ . By a solution of equation (1), we mean a function  $x \in C([T_x, \infty))$ ,  $T_x \geq t_0$ , such that  $rz' \in C^1([T_x, \infty))$  and  $x$  satisfies (1) on  $[T_x, \infty)$ . We consider only those solutions of (1) which satisfy  $\sup\{|x(t)| : t \geq T\} > 0$  for all  $T \geq T_x$  and assume that (1) possesses such solutions. A solution of (1) is called oscillatory if it does not have the largest zero on  $[T_x, \infty)$ , otherwise, it is called non-oscillatory. Equation (1) is said to be oscillatory if all its solutions are oscillatory.

Very recently, Baculíková and Džurina [4] established several oscillation theorems for equation (1) via its comparison with associated first-order delay differential equations in the case when, in addition to  $(H_1)$ - $(H_3)$ , condition

$$\lim_{t \rightarrow \infty} R(t) = \infty \quad (3)$$

is satisfied. Assuming

$$\int_{t_0}^{\infty} r^{-1/\gamma}(t) dt = \infty$$

instead of (3), Baculíková and Džurina [5] extended results of [4] to a nonlinear neutral differential equation

$$(r(t) [(x(t) + p(t)x(\tau(t)))']^\gamma)' + q(t)x^\beta(\sigma(t)) = 0,$$

where  $\gamma$  and  $\beta$  are ratios of positive odd integers. Using a similar idea, Baculíková et al. [6] studied the oscillation of an even-order neutral differential equation

$$\left( \left[ (x(t) + p(t)x(\tau(t)))^{(n-1)} \right]^\gamma \right)' + q(t)x^\gamma(\sigma(t)) = 0,$$

where  $n \geq 2$  is an even number and  $\gamma \geq 1$  is a ratio of two odd positive integers. Han et al. [10] employed Riccati transformation and integral averaging techniques to investigate the oscillation of a nonlinear differential equation

$$(r(t)\psi(x(t)) [(x(t) + p(t)x(\tau(t)))']^\gamma)' + q(t)f(x(\sigma(t))) = 0$$

in the case when  $(H_1)$ - $(H_2)$  and  $\int_{t_0}^{\infty} r^{-1/\gamma}(t) dt < \infty$  hold,  $\tau(t) \leq t$ ,  $\sigma(t) \leq t$ ,  $\sigma'(t) > 0$ , and

$$\text{either } \sigma(t) \geq \tau(t), \quad \text{or } \sigma(t) \leq \tau(t). \quad (4)$$

Li et al. [14] studied oscillation of equation (1) under the assumptions that (2) holds,  $\tau$  and  $\sigma$  are strictly increasing,  $p(t) > 1$ , and (4) is satisfied. Li et al. analyzed oscillatory properties of equation (1) in the case where  $(H_1)$ - $(H_3)$  hold,  $\tau(t) \geq t$ , and  $\sigma(t) \geq t$ . They derived a sufficient condition which ensures that solutions of equation (1) are either oscillatory or satisfy  $\lim_{t \rightarrow \infty} x(t) = 0$  for the case where (2) holds and  $0 \leq p(t) \leq p_1 < 1$  [15, Theorem 3.8]. Finally, we note that Hasanbulli and Rogovchenko [11] obtained new oscillation results for a nonlinear neutral differential equation

$$(r(t)[x(t) + p(t)x(t - \tau)])' + q(t)f(x(t), x(\sigma(t))) = 0$$

in the case where  $0 \leq p(t) \leq 1$ ,  $\sigma(t) \leq t$ ,  $\sigma'(t) > 0$ , and (3) holds.

We stress that results in [4, 5, 6, 11] cannot be applied to (1) in the case where (2) holds. The purpose of this paper is to extend a new method for the analysis of the oscillation of equation (1) via comparison principles suggested by Baculiková and Džurina [4] for the study of (1) under the assumption (2).

## 2 Main results

In what follows, all inequalities are assumed to hold eventually, that is, for all  $t$  large enough. We also use the notation  $y(t) := -u(t) := r(t)z'(t)$ ,  $Q(t) := \min\{q(t), q(\tau(t))\}$ , and  $\delta(t) := \int_t^\infty (r(s))^{-1} ds$ .

**Theorem 1** *Assume that  $(H_1)$ - $(H_3)$  and (2) hold, and let  $t_1$  be large enough. Suppose that there exist two functions  $\eta, \xi \in C([t_0, \infty))$  such that  $\eta(t) \leq \sigma(t) \leq \xi(t)$  and  $\lim_{t \rightarrow \infty} \eta(t) = \infty$ . If the first-order neutral differential inequalities*

$$\left( y(t) + \frac{p_0}{\tau_0} y(\tau(t)) \right)' + Q(t) (R(\eta(t)) - R(t_1)) y(\eta(t)) \leq 0 \quad (5)$$

and

$$\left( w(t) + \frac{p_0}{\tau_0} w(\tau(t)) \right)' - Q(t) \delta(\xi(t)) w(\xi(t)) \geq 0 \quad (6)$$

have no positive solutions, equation (1) is oscillatory.

**Proof.** Assume that (1) has a non-oscillatory solution  $x(t)$  on  $[t_0, \infty)$ . Without loss of generality, we can suppose that  $x(t)$  is eventually positive. As in the proof of [4, Theorem 1], one arrives at the inequality

$$(r(t)z'(t))' + \frac{p_0}{\tau_0} (r(\tau(t))z'(\tau(t)))' + Q(t)z(\sigma(t)) \leq 0. \quad (7)$$

Equation (1) yields that, for some  $t_1$  large enough and for all  $t \geq t_1$ , either

$$z'(t) > 0, \quad (r(t)z'(t))' < 0, \quad (8)$$

or

$$z'(t) < 0, \quad (r(t)z'(t))' < 0. \quad (9)$$

Assume first that (8) holds. Inequality (7) and the fact that  $\eta(t) \leq \sigma(t)$  yield

$$(r(t)z'(t))' + \frac{p_0}{\tau_0} (r(\tau(t))z'(\tau(t)))' + Q(t)z(\eta(t)) \leq 0.$$

It follows from condition (8) that

$$z(t) \geq \int_{t_1}^t \frac{r(s)z'(s)}{r(s)} ds \geq r(t)z'(t) \int_{t_1}^t \frac{1}{r(s)} ds,$$

for all sufficiently large  $t$ . Therefore,  $y(t)$  is a positive solution of inequality (5), which contradicts our assumption that this inequality has no positive solutions.

Consider now the second case. It follows from (9) that

$$z'(s) \leq \frac{r(t)z'(t)}{r(s)} \quad \text{for all } s \geq t,$$

which, upon integration, leads to

$$z(l) \leq z(t) + r(t)z'(t) \int_t^l \frac{1}{r(s)} ds.$$

Passing to the limit as  $l \rightarrow \infty$ , we conclude that

$$z(t) + r(t)z'(t) \int_t^\infty \frac{1}{r(s)} ds \geq 0.$$

Therefore,

$$z(t) \geq -r(t)z'(t)\delta(t). \quad (10)$$

It follows from (7) and condition  $\sigma(t) \leq \xi(t)$  that

$$(r(t)z'(t))' + \frac{p_0}{\tau_0} (r(\tau(t))z'(\tau(t)))' + Q(t)z(\xi(t)) \leq 0. \quad (11)$$

Then,  $y(t) < 0$  and, by virtue of (10) and (11),

$$\left( y(t) + \frac{p_0}{\tau_0} y(\tau(t)) \right)' - Q(t)\delta(\xi(t))y(\xi(t)) \leq 0.$$

Writing the latter inequality in the form

$$-\left( y(t) + \frac{p_0}{\tau_0} y(\tau(t)) \right)' - Q(t)\delta(\xi(t))(-y(\xi(t))) \geq 0,$$

we deduce that  $u(t)$  is a positive solution of the inequality (6), which, according to our assumption, has no positive solutions. Therefore, equation (1) is oscillatory. ■

Under additional conditions on the coefficients of (1), one can deduce from Theorem 1 a number of oscillation criteria applicable to different classes of equations. In what follows, the notation  $\tau^{-1}$  stands for the inverse of the function  $\tau$ .

**Theorem 2** *Assume that  $(H_1)$ - $(H_3)$  and (2) hold, and let  $t_1$  be large enough. Suppose that there exist two functions  $\eta, \xi \in C([t_0, \infty))$  such that  $\eta(t) \leq \sigma(t) \leq \xi(t)$  and  $\lim_{t \rightarrow \infty} \eta(t) = \infty$ . Assume also that*

$$\tau(t) \geq t. \quad (12)$$

*If the first-order differential inequalities*

$$h'(t) + \frac{\tau_0}{\tau_0 + p_0} Q(t) (R(\eta(t)) - R(t_1)) h(\eta(t)) \leq 0 \quad (13)$$

*and*

$$f'(t) - \frac{\tau_0}{\tau_0 + p_0} Q(t) \delta(\xi(t)) f(\tau^{-1}(\xi(t))) \geq 0 \quad (14)$$

*have no positive solutions, equation (1) is oscillatory.*

**Proof.** Suppose that (1) has a non-oscillatory solution  $x(t)$  defined on  $[t_0, \infty)$ . As above, we can assume that  $x(t)$  is eventually positive. Following the same lines as in [4, Theorem 2], we conclude that the inequality (13) has a positive solution, which contradicts our assumption. On the other hand, we have shown in Theorem 1 that the function  $u(t)$  is positive, increasing, and satisfies (6). It follows from (12) that

$$w(t) \leq u(\tau(t)) \left(1 + \frac{p_0}{\tau_0}\right), \quad (15)$$

where

$$w(t) := u(t) + \frac{p_0}{\tau_0} u(\tau(t)). \quad (16)$$

Substituting (15) into (6), we conclude that  $w(t)$  is a positive solution of (14), which contradicts the fact that this inequality does not have positive solutions. The proof is complete. ■

Combining Theorem 2 with the oscillation criteria presented in Ladde et al. [12, Theorems 2.1.1 and 2.4.1], we obtain the following result.



**Corollary 3** Assume that conditions  $(H_1)$ - $(H_3)$ , (2) and (12) are satisfied. Suppose further that there exist two functions  $\eta, \xi \in C([t_0, \infty))$  such that  $\eta(t) < t$ ,  $\xi(t) > \tau(t)$ ,  $\eta(t) \leq \sigma(t) \leq \xi(t)$ , and  $\lim_{t \rightarrow \infty} \eta(t) = \infty$ . If, for all sufficiently large  $t_1 \geq t_0$ ,

$$\liminf_{t \rightarrow \infty} \int_{\eta(t)}^t Q(s) (R(\eta(s)) - R(t_1)) ds > \frac{\tau_0 + p_0}{\tau_0 e} \quad (17)$$

and

$$\liminf_{t \rightarrow \infty} \int_t^{\tau^{-1}(\xi(t))} Q(s) \delta(\xi(s)) ds > \frac{\tau_0 + p_0}{\tau_0 e}, \quad (18)$$

equation (1) is oscillatory.

**Proof.** By [12, Theorem 2.1.1], assumption (17) ensures that the differential inequality (13) has no positive solutions. On the other hand, by [12, Theorem 2.4.1], condition (18) guarantees that the differential inequality (14) has no positive solutions. Application of Theorem 2 yields the result. ■

**Theorem 4** Assume that conditions  $(H_1)$ - $(H_3)$  and (2) are satisfied, and let  $t_1$  be large enough. Suppose that there exist two functions  $\eta, \xi \in C([t_0, \infty))$  such that  $\eta(t) \leq \sigma(t) \leq \xi(t)$  and  $\lim_{t \rightarrow \infty} \eta(t) = \infty$ . Finally, assume that

$$\tau(t) \leq t. \quad (19)$$

If the first-order differential inequalities

$$h'(t) + \frac{\tau_0}{\tau_0 + p_0} Q(t) (R(\eta(t)) - R(t_1)) h(\tau^{-1}(\eta(t))) \leq 0 \quad (20)$$

and

$$f'(t) - \frac{\tau_0}{\tau_0 + p_0} Q(t) \delta(\xi(t)) f(\xi(t)) \geq 0 \quad (21)$$

have no positive solutions, equation (1) is oscillatory.

**Proof.** Assume again that equation (1) has on  $[t_0, \infty)$  a non-oscillatory solution  $x(t)$  which is eventually positive. Along the same lines as in [4, Theorem 3], we deduce that the inequality (20) has a positive solution, which contradicts our assumption. On the other hand, it has been established in



Theorem 1 that the function  $y(t)$  is positive, increasing, and satisfies the inequality (6). By virtue of (19), the inequality

$$w(t) \leq u(t) \left( 1 + \frac{p_0}{\tau_0} \right)$$

holds for the function  $w(t)$  defined by (16). Substituting this into (6), we conclude that  $w(t)$  is a positive solution of (21), which contradicts our assumption. The proof is complete. ■

Combining Theorem 4 with results in Ladde et al. [12, Theorems 2.1.1 and 2.4.1], we obtain the following oscillation criterion.

**Corollary 5** *Assume that conditions  $(H_1)$ - $(H_3)$ , (2) and (19) are satisfied. Suppose further that there exist two functions  $\eta, \xi \in C([t_0, \infty))$  such that  $\eta(t) < \tau(t)$ ,  $\xi(t) > t$ ,  $\eta(t) \leq \sigma(t) \leq \xi(t)$ , and  $\lim_{t \rightarrow \infty} \eta(t) = \infty$ . If, for all sufficiently large  $t_1 \geq t_0$ ,*

$$\liminf_{t \rightarrow \infty} \int_{\tau^{-1}(\eta(t))}^t Q(s) (R(\eta(s)) - R(t_1)) ds > \frac{\tau_0 + p_0}{\tau_0 e} \quad (22)$$

and

$$\liminf_{t \rightarrow \infty} \int_t^{\xi(t)} Q(s) \delta(\xi(s)) ds > \frac{\tau_0 + p_0}{\tau_0 e}, \quad (23)$$

equation (1) is oscillatory.

**Proof.** By virtue of [12, Theorem 2.1.1], condition (22) ensures that differential inequality (20) has no positive solutions. On the other hand, it follows from [12, Theorem 2.4.1] that condition (23) guarantees that the differential inequality (21) has no positive solutions. Application of Theorem 4 completes the proof. ■

### 3 Examples and discussion

The following two examples illustrate applications of theoretical results in the previous section.

**Example 6** *For  $t \geq 1$ , consider a second-order neutral differential equation*

$$(t^2[x(t) + p_0x(\alpha t)]')' + q_0x(\beta t) = 0, \quad (24)$$

where  $\alpha$ ,  $p_0$ ,  $q_0$ , and  $\beta$  are positive constants,  $\beta > \alpha > 1$ . Let  $\eta(t) = t/\alpha$  and  $\xi(t) = \beta t$ . Application of Corollary 3 yields that all solutions of equation (24) are oscillatory provided that

$$\frac{q_0}{\beta} \ln \frac{\beta}{\alpha} > \frac{\alpha + p_0}{\alpha e}.$$

**Example 7** For  $t \geq 1$ , consider a second-order neutral delay differential equation

$$\left( e^t \left[ x(t) + \frac{1}{2} x \left( t - \frac{\pi}{4} \right) \right] \right)' + 12\sqrt{65}e^t x \left( t - \frac{1}{8} \arcsin \frac{\sqrt{65}}{65} \right) = 0. \quad (25)$$

Let  $\eta(t) = t - \pi/2$  and  $\xi(t) = t + \pi/4$ . Taking into account that  $R(t) = e^{-1} - e^{-t}$ ,  $Q(t) = 12\sqrt{65}e^{t-\pi/4}$ ,  $\delta(t) = e^{-t}$ , and  $\tau_0 = 1$ , we conclude that

$$\begin{aligned} \liminf_{t \rightarrow \infty} \int_{\tau^{-1}(\eta(t))}^t Q(s) (R(\eta(s)) - R(t_1)) ds \\ = \liminf_{t \rightarrow \infty} \int_{t-\pi/4}^t 12\sqrt{65}e^{s-\pi/4} (e^{-t_1} - e^{-s+\pi/2}) ds > \frac{3}{2e} \end{aligned}$$

and

$$\begin{aligned} \liminf_{t \rightarrow \infty} \int_t^{\xi(t)} Q(s) \delta(\xi(s)) ds \\ = \liminf_{t \rightarrow \infty} \int_t^{t+\pi/4} 12\sqrt{65}e^{s-\pi/4} e^{-s-\pi/4} ds > \frac{3}{2e}. \end{aligned}$$

By Corollary 5, all solutions to equation (25) oscillate. As a matter of fact, one such solution is  $x(t) = \sin 8t$ .

**Remark 8** Oscillation criteria established in this paper for equation (1) complement, on one hand, theorems reported by Baculíková and Džurina [4] and Hasanbulli and Rogovchenko [11] because we use assumption (2) rather than (3) and, on the other hand, those by Li et al. [14] since our criteria can be applied to the case where  $0 \leq p(t) \leq p_0 < \infty$ .

**Remark 9** Using methods different from those exploited in [10, 11, 14, 15], we improve results of Han et al. [10] and Li et al. [15, Theorem 3.8] by removing assumptions  $\sigma(t) \leq \tau(t) \leq t$  or  $t \geq \sigma(t) \geq \tau(t)$  imposed in the cited papers and providing sufficient conditions which ensure that all solutions of (1) are oscillatory.

**Remark 10** As mentioned by Baculíková and Džurina [4, Remark 4], assumptions  $(H_2)$  and  $(H_3)$  on functional arguments do not specify whether  $\tau(t)$  is a delayed or advanced argument. Therefore  $\sigma(t)$  can be a delayed argument and  $\sigma(t) - t$  can even oscillate. However, to achieve such flexibility, we are forced to require, as in [4, Remark 4], monotonicity of  $\tau$  and that  $\tau \circ \sigma = \sigma \circ \tau$ . The question regarding the study of oscillatory properties of equation (1) with other methods that do not require assumption  $(H_3)$  remains open at the moment.

**Remark 11** Note that by using the inequalities

$$x_1^\alpha + x_2^\alpha \geq (x_1 + x_2)^\alpha, \quad \text{for } 0 < \alpha \leq 1 \text{ and all } x_1, x_2 \in [0, \infty),$$

and

$$x_1^\alpha + x_2^\alpha \geq \frac{1}{2^{\alpha-1}}(x_1 + x_2)^\alpha, \quad \text{for } \alpha \geq 1 \text{ and all } x_1, x_2 \in [0, \infty),$$

results reported in this paper can be extended to a second-order half-linear neutral differential equation

$$(r(t) ([x(t) + p(t)x(\tau(t))]')^\alpha)' + q(t)x^\alpha(\sigma(t)) = 0,$$

where  $\alpha > 0$  is a ratio of odd positive integers.

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